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1. OSD14.1-AU1: Biometrics for Human-machine Team Feedback in Autonomous Systems

   Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

   This topic is supported under National Robotics Initiatives (NRI). OBJECTIVE: Develop and use biometrics that provides feedback about the status of human-machine team in autonomous systems. DESCRIPTION: Intense workload and short deadlines place a great deal of stress on warfighters applying computer systems to complete their mission. Biometric techniques show promise for detecting variatio ...

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2. OSD14.1-AU2: Evaluating the Performance and Progress of Learning-enabled Systems

   Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

   This topic is supported under National Robotics Initiatives (NRI). OBJECTIVE: Develop methodology to evaluate and measure the performance and progress for learning enabled systems. DESCRIPTION: A long term goal of machine learning is to develop systems that learn complex behaviors with minimal human oversight. However, future systems that incorporate learning strategies will not necessarily ...

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3. OSD14.1-AU3: Evaluating Mixed Human/Robot Team Performance

   Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

   This topic is supported under National Robotics Initiatives (NRI). OBJECTIVE: Develop methodology to evaluate mixed human/robot team performance DESCRIPTION: Introducing robotic assets to a military or civilian unit should increase the level of performance for the team. We evaluate human teams by scoring their performance on specific tasks; they can be a single score for the team, or an aggr ...

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4. OSD14.1-AU4: Safety Testing for Autonomous Systems in Simulation

   Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

   This topic is supported under National Robotics Initiatives (NRI). OBJECTIVE: The Army is interested in adding autonomy to its vehicle convoys [1], but how can we certify that these autonomous algorithms are safe? Currently, live testing of full vehicle systems is the only acceptable method, but even after hundreds of hours of successful live testing, a single hidden failure point in the algor ...

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5. OSD14.1-AU5: Distributed Visual Surveillance for Unmanned Ground Vehicles

Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

This topic is supported under National Robotics Initiatives (NRI). OBJECTIVE: Develop a system to identify, classify, and analyze visual data from unmanned ground vehicles and stationary visual surveillance sources to enable real-time on-board decisions and system-wide planning regarding route, speed, and tasks. DESCRIPTION: Distributed visual surveillance has a major role in the future of ...

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6. OSD14.1-IA1: Obfuscation to Thwart Un-Trusted Hardware

Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

OBJECTIVE: To develop innovative methods for mutating or obfuscating the processes of network security appliances or tactical communication systems. To make the path of the processes and data through hardware non deterministic, thereby thwarting any supply chain attacks that rely on the deterministic nature of computing to exfiltrate data and compromise operations. To mask the data and processes s ...

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7. OSD14.1-IA2: Detecting Malicious Circuits in IP-Core

Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

OBJECTIVE: Develop technologies and tools for detecting potential malicious/backdoor logics in hardware IP-core, toward reducing supply-chain vulnerability in embedded computing and system on chip environment. DESCRIPTION: This topic solicits the development of technologies and tools which perform analysis on gate-level netlist of hardware IP-core to identify potentially malicious wires and log ...

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8. AF141-001: Non-Silicon and Non-Boron based Leading Edges for Hypersonic Vehicles

Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

OBJECTIVE: Identify and demonstrate a new material system with suitable material properties to realize the advanced leading edges for use in reusable or long flight time hypersonic vehicles. DESCRIPTION: Air Force-relevant applications include but not limited to sharp leading edges, rocket nozzles, throats and engine combustion parts are key components that enable hypersonic flight. These lead ...

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9. AF141-002: Epitaxial Technologies for SiGeSn High Performance Optoelectronic Devices

Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

OBJECTIVE: Develop SiGeSn epitaxy on silicon and germanium substrates for new degrees of freedom in optoelectronic devices operating in the wavelength range between 2.0 and 5.0 micrometers. DESCRIPTION: Conventional mid-infrared materials based on the III-V (GaInSb) and the II-VI (HgCdTe) materials are relatively expensive and incompatible with silicon-based integrated circuit processing. S ...

SBIR Department of DefenseAir Force

10. AF141-003: Variable Precision Filters

Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

OBJECTIVE: The development of innovative mathematical techniques for the design of digital filters allowing trade-offs between accuracy, precision and memory. DESCRIPTION: The design of finite impulse response (FIR or non-recursive) and infinite impulse response (IIR or recursive) digital filters has a long history and, over the years, many methods have been developed to design FIR, IIR filt ...

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